

## Drive Specifications

## Performance

| Repeatability: | $\pm 5$ arc-seconds (unidirectional), typical unloaded motor |
| :--- | :--- |
| Accuracy: | $\pm 5$ arc-minutes (bidirectional), typical unloaded motor |
| Step-to-Step Accuracy: $\pm 20$ arc-seconds (unidirectional), unloaded motor |  |
| Waveform Selection: | pure sine, $+-2 \%,+-4 \%$ 3rd harmonic included |
| Resolution: | selectable25600,12800,6400, 3200, $1600,800,400,50000,25000,10000,5000,1000,36000,18000$ |
|  | microstep per revolution |

## Amplifier

Type: $\quad 2$ phases 20Khz frequency, variable duty cycle PWM, current controlled H bridge MOSFET construction. Protection: current over 7 amp phase to phase and phase to ground. When condition(s) occur, the drive is shut down.

Power must be recycled to resume operation.
Auto standby: When the signal is high, motor current drops to $50 \%$ of preset value if no pulses are received for 1 second.
Rated current is resumed upon receipt of next step pulse.
Self test: dip switch selectable. The motor rotates 0.4 revolutions per second
Step: Input, optical isolated, 470 ohm resistor connects to diode on the drive. Accepts $5 \mathrm{~V}, 10 \mathrm{~mA}$ signal (typical). minimum 250 nanosecond pulse width $50 \%$ duty cycle.
Direction: Input, optical isolated. Accept 5V, 10 mA signal (typical). 50 usec min. prior to the step signal changing.
Disable: Input, accept $5 \mathrm{~V}, 10 \mathrm{mAsignal}$ typical. The motor power is off when signal stays high, 1 msec minimum.
Fault output: open collector, 5 V typical, 4 mA maximum sink current. The signal is low what fault.
Current: $\quad \mathrm{P} / \mathrm{N}: ~ \mathrm{SD}, 0.5-1.5 \mathrm{amp}$ peak to preak. P/N: SD-H 0.5-3 amp for high power at 25 deg . C ambient. No external heat sink required. One external resistor sets current.
Over temperature: junction temperature reaches 165 deg. C in the power device(s). The drive will shut down.

## Motors

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\begin{array}{ll}
\text { Type: } & 2 \text { phase hybrid permanent magnet } 1.8 \text { degree stepping motors } \\
\text { Size: } & \text { NEMA17-23recommended } \\
\text { Leads: } & 4,6,8 \text { wires. }
\end{array}
$$

## Environmental

Operating : 0 to $70^{\circ} \mathrm{C}, 0$ to $95 \%$ humidity, non-condensing
Storage: -40 to $+80^{\circ} \mathrm{C}, 0$ to $95 \%$ humidity, non-condensing
Power: 12-24 VDC single supply or
7.5 V to 12 V and $12-40 \mathrm{~V}$ dual supplies

| P/N | SD |  | SD-H |  |
| :--- | :--- | :--- | :--- | :--- |
| Vmotor | 24 V | 40 V | 24 V | 40 V |
| VDD | 24 V | $7.5-12 \mathrm{~V}$ | 24 V | $7.5-12 \mathrm{~V}$ |
| Max. Current | 1.5 A | 1.5 A | 3 A | 3 A |

See table on right for prodcts voltage and current rating
Physical Dimension : 2.4" X 2.4" X $0.5^{\prime \prime}$

## Typical Connection:



